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$y(t)$. Assuming a
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limitations of
the open-loop
controller,
control theory
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feedback. A closed-loop controller uses feedback to control states or outputs of a dynamical system. Its name comes from the information path in the system: process inputs (e.g., voltage applied to an

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electric motor) have an effect on the process outputs (e.g., speed or torque of the motor), which is measured with ...

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