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This text is intended for an advanced undergraduate (having taken linear algebra and multivariable calculus). It provides the necessary background for a more abstract course in differential geometry. The inclusion of diagrams is done without sacrificing the rigor of the material. For all readers interested in differential geometry.

This book is intended as a first rigorous course in geometry. As the title indicates, we have adopted Birkhoff's metric approach (i.e., through use of real numbers) rather than Hilbert's synthetic approach to the subject. Throughout the text we illustrate the various axioms, definitions, and theorems with models ranging from the familiar Cartesian plane to the Poincare upper half plane, the Taxicab plane, and the Moulton plane. We hope that through an intimate acquaintance with examples (and a model is just an example), the reader will obtain a real feeling and intuition for non Euclidean (and in particular, hyperbolic) geometry. From a pedagogical viewpoint this approach has the advantage of reducing the reader's tendency to reason from a picture. In addition, our students have found the strange new world of the non-Euclidean geometries both interesting and exciting. Our basic approach is to introduce and develop the various axioms slowly, and then, in a departure from other texts, illustrate major definitions and axioms with two or three models. This has the twin advantages of showing the richness of the concept being discussed and of enabling the reader to picture the idea more clearly. Furthermore, encountering models which do not satisfy the axiom being introduced or the hypothesis of the theorem being proved often sheds more light on the relevant concept than a myriad of cases which do.

Our first knowledge of differential geometry usually comes from the study of the curves and surfaces in \mathbb{R}^3 that arise in calculus. Here we learn about line and surface integrals, divergence and curl, and the various forms of Stokes' Theorem. If we are fortunate, we may encounter curvature and such things as the Serret-Frenet formulas. With just the basic tools from multivariable calculus, plus a little knowledge of linear algebra, it is possible to begin a much richer and rewarding study of differential geometry, which is what is presented in this book. It starts with an introduction to the classical differential geometry of curves and surfaces in Euclidean space, then leads to an introduction to the Riemannian geometry of more general manifolds, including a look at Einstein spaces. An important bridge from the low-dimensional theory to the general case is provided by a chapter on the intrinsic geometry of surfaces. The first half of the book, covering the geometry of curves and surfaces, would be suitable for a one-semester undergraduate course. The local and global theories of curves and surfaces are presented, including detailed discussions of surfaces of rotation, ruled surfaces, and minimal surfaces. The second half of the book, which could be used for a more advanced course, begins with an introduction to differentiable manifolds, Riemannian structures, and the

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curvature tensor. Two special topics are treated in detail: spaces of constant curvature and Einstein spaces. The main goal of the book is to get started in a fairly elementary way, then to guide the reader toward more sophisticated concepts and more advanced topics. There are many examples and exercises to help along the way. Numerous figures help the reader visualize key concepts and examples, especially in lower dimensions. For the second edition, a number of errors were corrected and some text and a number of figures have been added.

Differential geometry arguably offers the smoothest transition from the standard university mathematics sequence of the first four semesters in calculus, linear algebra, and differential equations to the higher levels of abstraction and proof encountered at the upper division by mathematics majors. Today it is possible to describe differential geometry as "the study of structures on the tangent space," and this text develops this point of view. This book, unlike other introductory texts in differential geometry, develops the architecture necessary to introduce symplectic and contact geometry alongside its Riemannian cousin. The main goal of this book is to bring the undergraduate student who already has a solid foundation in the standard mathematics curriculum into contact with the beauty of higher mathematics. In particular, the presentation here emphasizes the consequences of a definition and the careful use of examples and constructions in order to explore those consequences.

One of the most widely used texts in its field, this volume introduces the differential geometry of curves and surfaces in both local and global aspects. The presentation departs from the traditional approach with its more extensive use of elementary linear algebra and its emphasis on basic geometrical facts rather than machinery or random details. Many examples and exercises enhance the clear, well-written exposition, along with hints and answers to some of the problems. The treatment begins with a chapter on curves, followed by explorations of regular surfaces, the geometry of the Gauss map, the intrinsic geometry of surfaces, and global differential geometry. Suitable for advanced undergraduates and graduate students of mathematics, this text's prerequisites include an undergraduate course in linear algebra and some familiarity with the calculus of several variables. For this second edition, the author has corrected, revised, and updated the entire volume.

In the past decade there has been a significant change in the freshman/ sophomore mathematics curriculum as taught at many, if not most, of our colleges. This has been brought about by the introduction of linear algebra into the curriculum at the sophomore level. The advantages of using linear algebra both in the teaching of differential equations and in the teaching of multivariate calculus are by now widely recognized. Several textbooks adopting this point of view are now available and have been widely adopted. Students completing the sophomore year now have a fair preliminary understanding of spaces of many dimensions. It should be apparent that courses on the junior level should draw upon and reinforce the concepts and skills learned during the previous year. Unfortunately, in differential geometry at least, this is usually not the case. Textbooks directed to students at this level generally restrict attention to 2-dimensional surfaces in 3-space rather than to surfaces of arbitrary dimension. Although most of the recent books do use linear algebra, it is only the algebra of \mathbb{R}^3 . The student's preliminary understanding of higher dimensions is not cultivated.

This text contains an elementary introduction to continuous groups and differential invariants; an extensive treatment of groups of motions in euclidean, affine, and riemannian geometry; more. Includes exercises and 62 figures.

Central topics covered include curves, surfaces, geodesics, intrinsic geometry, and the Alexandrov global angle comparison theorem Many nontrivial and

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original problems (some with hints and solutions) Standard theoretical material is combined with more difficult theorems and complex problems, while maintaining a clear distinction between the two levels

A thoroughly revised second edition of a textbook for a first course in differential/modern geometry that introduces methods within a historical context.

This text presents a graduate-level introduction to differential geometry for mathematics and physics students. The exposition follows the historical development of the concepts of connection and curvature with the goal of explaining the Chern-Weil theory of characteristic classes on a principal bundle. Along the way we encounter some of the high points in the history of differential geometry, for example, Gauss' Theorema Egregium and the Gauss-Bonnet theorem. Exercises throughout the book test the reader's understanding of the material and sometimes illustrate extensions of the theory. Initially, the prerequisites for the reader include a passing familiarity with manifolds. After the first chapter, it becomes necessary to understand and manipulate differential forms. A knowledge of de Rham cohomology is required for the last third of the text. Prerequisite material is contained in author's text *An Introduction to Manifolds*, and can be learned in one semester. For the benefit of the reader and to establish common notations, Appendix A recalls the basics of manifold theory. Additionally, in an attempt to make the exposition more self-contained, sections on algebraic constructions such as the tensor product and the exterior power are included. Differential geometry, as its name implies, is the study of geometry using differential calculus. It dates back to Newton and Leibniz in the seventeenth century, but it was not until the nineteenth century, with the work of Gauss on surfaces and Riemann on the curvature tensor, that differential geometry flourished and its modern foundation was laid. Over the past one hundred years, differential geometry has proven indispensable to an understanding of the physical world, in Einstein's general theory of relativity, in the theory of gravitation, in gauge theory, and now in string theory. Differential geometry is also useful in topology, several complex variables, algebraic geometry, complex manifolds, and dynamical systems, among other fields. The field has even found applications to group theory as in Gromov's work and to probability theory as in Diaconis's work. It is not too far-fetched to argue that differential geometry should be in every mathematician's arsenal.

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